

### Homework Set 6

1. Determine matched inner and outer solutions of the following singularly perturbed boundary value problem:

$$\varepsilon y'' + y' + xy^2 = 0, \quad y(0) = y(1) = 1, \quad 0 < \varepsilon \ll 1.$$

Plot your matched solutions for  $\varepsilon = 0.1$  and  $\varepsilon = 0.01$ . In each case, label the boundary layer.

2. Let's recast the swing-pumping problem of Homework 4 as an autonomous nonlinear system. This problem involved a pendulum whose length  $r(t)$  is deliberately varied by the swinger as a function of the pendulum angle  $\theta(t)$  to the vertical. As discussed in HW4, the pendulum obeys the ODE

$$r\theta'' + 2r'\theta' + g\theta = 0. \quad (*)$$

In solving this problem, we found that to efficiently pump energy into the swinging motion,  $r$  should be longest in the middle of the downswing (when  $\theta\theta' < 0$ ) and shortest in the middle of the upswing ( $\theta\theta' > 0$ ). If length and time are nondimensionalized such that the mean pendulum length and period are both 1 (this will also make the nondimensional gravity  $g = 1$  in (\*)), a parametric form with this property is:

$$r = 1 - \varepsilon\theta\theta' / (\theta^2 + \theta'^2), \quad 0 < \varepsilon \ll 1. \quad (*')$$

- (a) Using the chain rule to express  $r'$  in terms of  $\theta$  and  $u$ , show that (\*) can be written as the following autonomous pair of ODEs for  $\theta(t)$  and  $u(t) = \theta'(t)$ :

$$\begin{aligned} \theta' &= u, \\ (r + 2u \frac{\partial r}{\partial u})u' &= -(2 \frac{\partial r}{\partial \theta} u^2 + \theta), \end{aligned}$$

where

$$r = 1 - \varepsilon \frac{\theta u}{\theta^2 + u^2}, \quad \frac{\partial r}{\partial \theta} = \varepsilon \frac{u(\theta^2 - u^2)}{(\theta^2 + u^2)^2}, \quad \frac{\partial r}{\partial u} = -\varepsilon \frac{\theta(\theta^2 - u^2)}{(\theta^2 + u^2)^2}.$$

- (b) Using Matlab (e.g. modifying the van der Pol example on the class web page), draw a phase portrait of this system for  $\varepsilon = 0.1$  over the region  $-1 < \theta, u < 1$  showing three orbits starting at  $u(0) = 0, \theta(0) = 0.3, 0.6, 0.9$  over  $0 < t < 2\pi$ , plotted as a set of points in the phase plane at times that are multiples of  $0.1\pi$ . We are restricting the region because the derivation of (\*) was only valid for small values of  $\theta$  (it would be easy to generalize the derivation to large  $\theta$ , but we won't do this here).
- (c) Construct a Poincare map for this system by considering the intersection of successive orbits with the ray  $u = 0, \theta > 0$  (again using the posted Matlab example script). Using the Poincare map, argue that the point  $u = \theta = 0$  should be regarded as an unstable fixed point or 'spiral'. By the way, this fixed point is not amenable to classical linear stability analysis since the right-hand side of the ODE system is not a continuously differentiable function of  $u$  and  $\theta$  at the fixed point.