

FFT
(Sine Transform)

1D

$$\begin{cases} -u_{xx} = f(x) \\ u=0 \text{ on } \partial\Omega \\ u(0)=0, u(1)=0 \end{cases} \Rightarrow \frac{1}{h^2} \begin{pmatrix} -2 & 1 & & \\ & 1 & \dots & \\ & & \dots & \\ & & & 1 & -2 \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{pmatrix} = \begin{pmatrix} F_1 \\ F_2 \\ \vdots \\ F_m \end{pmatrix}$$

Let $R = \begin{bmatrix} \sin(\pi x_1) & \sin(2\pi x_1) & \dots & \sin(m\pi x_1) \\ \sin(\pi x_2) & \sin(2\pi x_2) & & \sin(m\pi x_2) \\ \vdots & \vdots & & \vdots \\ \sin(\pi x_m) & \sin(2\pi x_m) & & \sin(m\pi x_m) \end{bmatrix}$

\uparrow evector of A \uparrow evector \uparrow evector

Note $R^2 = I \cdot \frac{1}{2h}$
 $\Rightarrow R^{-1} = 2h R$

$h = \frac{1}{m+1}$

Evector Decomposition of A:

$$\lambda_j = \frac{2}{h^2} (\cos(j\pi h) - 1) \Rightarrow A = R \Lambda R^{-1}$$

$$\Lambda = \begin{pmatrix} \lambda_1 & & \\ & \lambda_2 & \\ & & \dots \\ & & & \lambda_j \dots \end{pmatrix}$$

m interior pts

With the decomposition:

$$Au = F$$

$$R \Lambda R^{-1} u = F$$

$$u = R \underbrace{\Lambda^{-1} R^{-1} F}_{\hat{F}} = \underbrace{R \hat{F}}_{\hat{u}}$$

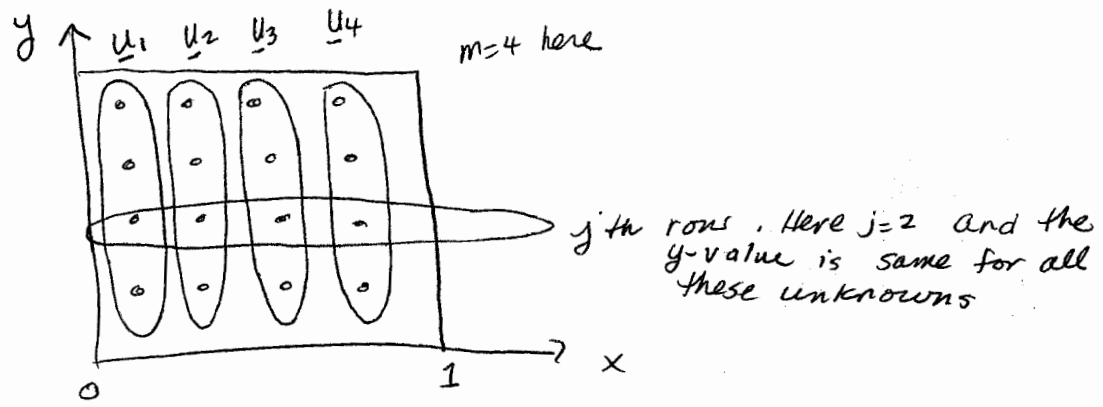
\Rightarrow Define $\hat{F} = R^{-1} F$
 $u = R \hat{u} \Rightarrow \hat{u} = R^{-1} u$

- Steps:
- (dst) 1) Compute $\hat{F} = R^{-1} F = 2h R F$ (transform F)
 - 2) Compute $\hat{u} = \Lambda^{-1} \hat{F}$ (diagonal multiply)
 - (dst) 3) Compute $u = R \hat{u}$ (inverse transform \hat{u})

2D Let's see how to use the 1D transform for $-u_{xx}$ to solve the 2D Poisson problem

$$\begin{cases} -u_{xx} - u_{yy} = f(x,y) \\ u=0 \text{ on } \partial\Omega \\ \Omega: \text{unit square} \end{cases}$$

Think of organizing groups of unknowns in the vertical direction (y-direction) as shown below.



Discretize

$$A \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{pmatrix} = \begin{pmatrix} F_1 \\ F_2 \\ \vdots \\ F_m \end{pmatrix}$$

Write A into its

horizontal and vertical stencil weights based on this ordering of the unknowns. think

$$A = \begin{matrix} & \begin{matrix} \bullet & \bullet & \bullet & \bullet \end{matrix} \\ \begin{matrix} | \\ | \\ | \\ | \end{matrix} & \begin{matrix} \bullet & \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet & \bullet \\ \bullet & \bullet & \bullet & \bullet \end{matrix} \\ & \begin{matrix} \bullet & \bullet & \bullet & \bullet \end{matrix} \end{matrix}$$

Weights: $1/4h^2$ (corners), $-2/h^2$ (center), $1/h^2$ (sides)

$$A_{\text{H}} = \frac{1}{h^2} \begin{pmatrix} -2I & I & & \\ I & -2I & I & \\ & \ddots & \ddots & \ddots \\ I & & I & -2I \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{pmatrix} + \begin{pmatrix} T & & & \\ & T & & \\ & & \ddots & \\ & & & T \end{pmatrix} \begin{pmatrix} u_1 \\ u_2 \\ \vdots \\ u_m \end{pmatrix}$$

↑ horizontal ↑ vertical

$$T = \begin{pmatrix} -2/h^2 & 1/h^2 & & \\ 1/h^2 & -2/h^2 & 1/h^2 & \\ & & \ddots & \ddots \\ 1/h^2 & & & -2/h^2 & 1/h^2 \end{pmatrix}$$

We know $TR = R - \Delta$! $R^{-1}T R = -\Delta$.

So multiply $A\underline{u} = \underline{F}$ on left and right sides by

$$\begin{pmatrix} R^{-1} & & \\ & R^{-1} & \\ & & \ddots \\ & & & R^{-1} \end{pmatrix} \text{ to get}$$

$$\begin{pmatrix} R^{-1} & & \\ & R^{-1} & \\ & & \ddots \\ & & & R^{-1} \end{pmatrix} \begin{pmatrix} -2I & I & & \\ I & -2I & I & \\ & & & I \\ & & & & -2I \end{pmatrix} \cdot \frac{1}{h^2} \begin{pmatrix} \underline{u}_1 \\ \underline{u}_2 \\ \vdots \\ \underline{u}_m \end{pmatrix} + \begin{pmatrix} R^{-1} & & \\ & R^{-1} & \\ & & \ddots \\ & & & R^{-1} \end{pmatrix} \begin{pmatrix} T & & \\ & T & \\ & & \ddots \\ & & & T \end{pmatrix} \left\{ \begin{pmatrix} R & & \\ & R & \\ & & \ddots \\ & & & R \end{pmatrix} \begin{pmatrix} \hat{u}_1 \\ \hat{u}_2 \\ \vdots \\ \hat{u}_m \end{pmatrix} \right\}$$

$$= \begin{pmatrix} R^{-1} & & \\ & R^{-1} & \\ & & \ddots \\ & & & R^{-1} \end{pmatrix} \begin{pmatrix} \underline{F}_1 \\ \underline{F}_2 \\ \vdots \\ \underline{F}_m \end{pmatrix}$$

$$\frac{1}{h^2} \begin{pmatrix} -2R^{-1} & R^{-1} & & \\ R^{-1} & -2R^{-1} & R^{-1} & \\ & & & R^{-1} \\ & & & & -2R^{-1} \end{pmatrix} \begin{pmatrix} \underline{u}_1 \\ \underline{u}_2 \\ \vdots \\ \underline{u}_m \end{pmatrix} + \begin{pmatrix} -\Delta \hat{u}_1 \\ -\Delta \hat{u}_2 \\ \vdots \\ -\Delta \hat{u}_m \end{pmatrix} = \begin{pmatrix} \hat{F}_1 \\ \hat{F}_2 \\ \vdots \\ \hat{F}_m \end{pmatrix}$$

Remember : $R^{-1}u_j = \hat{u}_j$

$$\frac{1}{h^2} \begin{pmatrix} -2\hat{u}_1 + \hat{u}_2 \\ \hat{u}_1 - 2\hat{u}_2 + \hat{u}_3 \\ \vdots \\ \hat{u}_{m-1} - 2\hat{u}_m \end{pmatrix} + \begin{pmatrix} -\Delta \hat{u}_1 \\ -\Delta \hat{u}_2 \\ \vdots \\ -\Delta \hat{u}_m \end{pmatrix} = \begin{pmatrix} \hat{F}_1 \\ \hat{F}_2 \\ \vdots \\ \hat{F}_m \end{pmatrix}$$

Look carefully at the j th row of each of the m blocked equations above to see that we get a tridiagonal system to solve for the \hat{u} -values in the j th row as shown in the figure (y-fixed for these values).

We get

$$\frac{1}{h^2} (-2\hat{u}_{1j} + \hat{u}_{2j}) + \lambda_j \hat{u}_{1j} = \hat{F}_{1j}$$

$$\frac{1}{h^2} (\hat{u}_{i-1,j} - 2\hat{u}_{ij} + \hat{u}_{i+1,j}) + \lambda_j \hat{u}_{ij} = \hat{F}_{ij}$$

$$\frac{1}{h^2} (\hat{u}_{m-1,j} - 2\hat{u}_{mj}) + \lambda_j \hat{u}_{mj} = \hat{F}_{mj}$$

$$\begin{pmatrix} \lambda_j - \frac{2}{h^2} & \frac{1}{h^2} & & & \\ \frac{1}{h^2} & \lambda_j - \frac{2}{h^2} & & & \\ & & \ddots & & \\ & & & \lambda_j - \frac{2}{h^2} & \frac{1}{h^2} \\ & & & \frac{1}{h^2} & \lambda_j - \frac{2}{h^2} \end{pmatrix} \begin{pmatrix} \hat{u}_{1j} \\ \hat{u}_{2j} \\ \vdots \\ \hat{u}_{mj} \end{pmatrix} = \begin{pmatrix} \hat{F}_{1j} \\ \hat{F}_{2j} \\ \vdots \\ \hat{F}_{mj} \end{pmatrix}$$

a tridiagonal system to solve for the \hat{u} values in the j th row (y_j fixed).

Let j vary from 1 to m and solve m independent linear tridiagonal systems.

Once, all m tridiagonals solved, we know \hat{u} all all m^2 interior points. Now, think that

\hat{u} is again organized by columns, $\hat{u}_1, \dots, \hat{u}_m$ and recover \underline{u} ,

$$\begin{pmatrix} \hat{u}_1 \\ \hat{u}_2 \\ \vdots \\ \hat{u}_m \end{pmatrix} = \underline{u} = \begin{pmatrix} R \hat{u}_1 \\ R \hat{u}_2 \\ \vdots \\ R \hat{u}_m \end{pmatrix}.$$